

Formal Methods & Functional Programming

Janis Hutz
<https://janishutz.com>

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“A funny quote by a professor”

- Prof. Dr. Professor Name, YEAR

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Summary of the Lectures

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1 Haskell

Haskell is a functional programming language. As such, its functions can be thought of as being similar to mathematical functions and as such are side-effect-free.

Haskell's type system is very robust and an interesting topic to learn about. The basic data types you already know from other programming languages are also present here. This includes all primitives like integers, floating point numbers, chars and booleans.

Strings are handled similarly to how C does it, in that strings are char arrays.

Arrays however are dynamic length in Haskell as opposed to many other statically typed programming languages.

Since Haskell is an imperative language (i.e. you describe *what* you want achieve) as opposed to a declarative language (i.e. you describe *how* you achieve what you want to achieve), there are no loops in Haskell, as loops don't appear in mathematical formulas and functions either. What we can do however is recursion and this is the main way of doing iterative work in Haskell.

Additionally, Haskell features *lazy evaluation* (i.e. statements are evaluated only as needed) as opposed to *eager evaluation* (i.e. statements are evaluated immediately).

In this course the Glasgow Haskell Compiler, short ghc is used. Installation is really easy (as long as you're on Linux)

1.1 The bad news: The syntax

In short: It's quite bad, but you will get used to it and some of the (arguably) poor looking syntax choices will start to make more sense.

You should use 2 space indents (yuck) and indents matter, just like in Python.

We can use binary functions in infix or prefix notation, i.e. `x `mod` z` and `mod x z` are equivalent.

For integers the following functions are available: Normal arithmetic operations `+`, `-`, `*`, `/`, `mod`, `abs`, as well as `^` which is used for exponentiation.

To use prefix notation on non-alphanumeric function names, wrap them in parenthesis like this: `(+) x z`. Using `+ x z` does not work.

We can use the normal comparison operators that return a boolean on evaluation. **Booleans** are `True` and `False`

2 Formal Reasoning

2.1 Formal proofs

Given a language like $\mathcal{L} = \{\oplus, \otimes, +, \times\}$, and derivation rules

- α : If $+$, then \otimes
- β : If $+$, then \times
- γ : If \otimes and \times , then \oplus
- δ : $+$ holds

or displayed using graphical notation:

$$\frac{+}{\otimes} \alpha \quad \frac{+}{\times} \beta$$

$$\frac{\otimes \quad \times}{\oplus} \gamma \quad \frac{-}{+} \delta$$

Rules like δ above are also commonly referred to as an *axiom*.

To prove \oplus in this language, we can either write the following or draw a derivation tree:

- $+$ holds by δ
- \otimes holds by α with 1.
- \times holds by β with 1.
- \oplus holds by γ with 2 and 3

Or as derivation tree

$$\frac{\frac{-}{+} \delta \quad \frac{-}{\otimes} \alpha \quad \frac{-}{\times} \beta}{\oplus} \gamma$$

2.2 Natural deduction

The rules from above here are used to construct derivations under assumptions, e.g. $A_1, \dots, A_n \vdash A$, which is read as “ A follows from A_1, \dots, A_n ”.

The derivations are always represented as derivation trees and a **proof** is a derivation whose root has no assumptions.

Since we have to prove a statement, we have to draw the derivation trees from the bottom up, with the goal of reaching an axiom or a rule that is an assumption using the other rules of the rule set.

2.3 Propositional logic

2.3.1 Syntax

Definition 2.3.1 For a set of variables \mathcal{V} , the **language of propositional logic** \mathcal{L}_P is the smallest set where

- $X \in \mathcal{L}_P$ if $X \in \mathcal{V}$
- $\perp \in \mathcal{L}_P$
- $A \wedge B \in \mathcal{L}_P$ if $A \in \mathcal{L}_P$ and $B \in \mathcal{L}_P$
- $A \vee B \in \mathcal{L}_P$ if $A \in \mathcal{L}_P$ and $B \in \mathcal{L}_P$
- $A \rightarrow B \in \mathcal{L}_P$ if $A \in \mathcal{L}_P$ and $B \in \mathcal{L}_P$

2.3.2 Semantics

Definition 2.3.2 (*Valuation*) $\sigma : \mathcal{V} \rightarrow \{\text{True}, \text{False}\}$ maps variables to truth values. They are the simple models (i.e. *interpretations*). **Valuations** is the set of valuations.

Definition 2.3.3 (*Satisfiability*) smallest relation $\models \subseteq \text{Valuations} \times \mathcal{L}_P$ such that

- $\sigma \models X$ if $\sigma(X) = \text{True}$
- $\sigma \models A \wedge B$ if $\sigma \models A$ and $\sigma \models B$
- $\sigma \models A \vee B$ if $\sigma \models A$ or $\sigma \models B$
- $\sigma \models A \rightarrow B$ if whenever $\sigma \models A$ then $\sigma \models B$

Definition 2.3.4 (*satisfiable formula*) A formula $A \in \mathcal{L}_P$ is **satisfiable** if $\sigma \models A$ for **some** valuation σ

Definition 2.3.5 (*tautology, valid formula*) A formula $A \in \mathcal{L}_P$ is **valid** (a **tautology**) if $\sigma \models A$ for **all** valuations σ

Definition 2.3.6 (*Semantic entailment*) $A_1, \dots, A_n \models A$ if $\forall \sigma$ we have $\sigma \models A_1, \dots, \sigma \models A_n$, then $\sigma \models A$

2.3.3 Requirements for a deductive system

The derivation rules (syntactic entailment) and truth tables (semantic entailment) should agree. For that we have two requirements, for $\Gamma = A_1, \dots, A_n$ a collection of formulas:

- **Soundness:** If $\Gamma \vdash A$ can be derived, then $\Gamma \models A$
- **Completeness:** If $\Gamma \models A$, then $\Gamma \vdash A$ can be derived

Decidability is also desirable, i.e. having checks of the attributes be of low complexity.

2.3.4 Natural deduction for propositional formulas

Definition 2.3.7 (*Sequent*) Is an assertion of form $A_1, \dots, A_n \vdash A$, with A, A_1, \dots, A_n being propositional formulas.

Intuition: A follows from the A_i and if the system is sound, the A_i semantically entail A .

Definition 2.3.8 (*Axiom*) is the starting point (usually the leaves) of the derivation trees and are usually of the form

$$\frac{}{\dots, A, \dots \vdash A} \text{ axiom}$$

i.e. when coming up with a derivation tree for a **proof**, we want to reach a leaf where A is contained in Γ .

Definition 2.3.9 (*Proof*) of A is a derivation tree with root $\vdash A$. If a deductive system is *sound*, then A is a tautology.

There are two kinds of rules, **introduce** and **eliminate** connectives. If you are confused about the order when applying them when coming up with a deduction tree, they are oriented top-down, so e.g. the introduction rule is inverted when coming up with the deduction tree.

If all rules are sound (i.e. they preserve semantic entailment), then the logic is sound.

2.3.5 Derivation rules for propositional logic

Remember that *E* means *elimination* and *I* means *introduction*, with *L* and *R* being the side (so *ER* means elimination on the right)

2.3.5.1 Conjunction

$$\frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \wedge B} \wedge\text{-I} \quad \frac{\Gamma \vdash A \wedge B}{\Gamma \vdash A} \wedge\text{-EL} \quad \frac{\Gamma \vdash A \wedge B}{\Gamma \vdash B} \wedge\text{-ER}$$

2.3.5.2 Disjunction

$$\frac{\Gamma \vdash A}{\Gamma \vdash A \vee B} \vee\text{-IL} \quad \frac{\Gamma \vdash B}{\Gamma \vdash A \vee B} \vee\text{-IR} \quad \frac{\Gamma \vdash A \vee B \quad \Gamma, A \vdash C \quad \Gamma, B \vdash C}{\Gamma \vdash C} \vee\text{-E}$$

2.3.5.3 Implication

$$\frac{\Gamma, A \vdash B}{\Gamma \vdash A \rightarrow B} \rightarrow\text{-I} \quad \frac{\Gamma \vdash A \rightarrow B \quad \Gamma \vdash A}{\Gamma \vdash B} \rightarrow\text{-E}$$

2.3.5.4 Others

$$\frac{\Gamma \vdash \perp}{\Gamma \vdash A} \perp\text{-E} \quad \frac{\Gamma \vdash \neg A \quad \Gamma \vdash A}{\Gamma \vdash B} \neg\text{-E} \quad \frac{\Gamma, \neg A \vdash \perp}{\Gamma \vdash A} \text{RAA} \quad \frac{}{\dots, A, \dots \vdash A} \text{ axiom}$$

2.4 First-Order Logic

2.4.1 Syntax

Definition 2.4.1 (*Signature*) consists of a set of function symbols \mathcal{F} and a set of predicate symbols \mathcal{P} , as well as their arities.

We write f^k (or p^k , for predicates) to indicate that it has *arity* $k \in \mathbb{N}$. Constant functions have arity 0, linear functions have arity 1, thus, the arity of a given function (or predicate) is given by the number of parameters to uniquely describe it, minus one.

Definition 2.4.2 (*Term*) is the terms of first-order logic is smallest set, where (with \mathcal{V} again a set of variables)

1. $x \in \text{Term}$ if $x \in \mathcal{V}$
2. $f^n(t_1, \dots, t_n) \in \text{Term}$ if $f^n \in \mathcal{F}$ and $t_i \in \text{Term}$, $\forall 1 \leq i \leq n$ (description of form of formulas)

Definition 2.4.3 (*Form*) is the formulas of first-order logic, is the smallest set where

1. $\perp \in \text{Form}$
2. $p^n(t_1, \dots, t_n) \in \text{Form}$ if $p^n \in \mathcal{P}$ and $t_j \in \text{Term}$, $\forall 1 \leq j \leq n$ (description of form of predicates)
3. $A \circ B \in \text{Form}$ if $A \in \text{Form}$, $B \in \text{Form}$ and $\circ \in \{\wedge, \vee, \rightarrow\}$ (i.e. formulas with logic symbols)
4. $Qx.A \in \text{Form}$ if $A \in \text{Form}$, $x \in \mathcal{V}$ and $Q \in \{\forall, \exists\}$ (i.e. formulas with quantifiers)

2.4.1.1 Binding

Definition 2.4.4 (*Bound variable*) A variable that occurs in a quantifier in scope (blue in example below)

Definition 2.4.5 (*Free variable*) A variable that is not bound by a quantifier in scope (red in example below)

Example 2.4.6 $(q(x) \vee \exists x. \forall y. p(f(x), z) \wedge q(a)) \vee \forall x. r(x, z, g(x))$

Definition 2.4.7 (α -conversion) A **bound** variable can be renamed at any time, but must preserve binding structure.

2.4.1.2 Precedences

$\neg > \wedge > \vee > \rightarrow$, with $>$ a total order of precedences. Quantifiers extend as far right as possible, bounded by the end of line or a going out of scope by closing parenthesis.

2.4.2 Semantics

Definition 2.4.8 (*Structure*) is a pair $\mathcal{S} = \langle U_{\mathcal{S}}, I_{\mathcal{S}} \rangle$, where $U_{\mathcal{S}}$ is the universe and it is a non-empty set and $I_{\mathcal{S}}$ is a mapping with

1. $I_{\mathcal{S}}(p^n)$ is an n -ary relation on $U_{\mathcal{S}}$ for $p^n \in \mathcal{P}$ (short $p^{\mathcal{S}}$)
2. $I_{\mathcal{S}}(f^n)$ is an n -ary (total) function on $U_{\mathcal{S}}$ for $f^n \in \mathcal{F}$ short $(f^{\mathcal{S}})$

Intuition: The $I_{\mathcal{S}}$ is essentially assigning to each predicate and formula its definition in the universe of the structure, noted as a relation.

Definition 2.4.9 (*Interpretation*) is a pair $\mathcal{I} = \langle \mathcal{S}, v \rangle$, with $v : \mathcal{V} \rightarrow U_{\mathcal{S}}$ a valuation

Intuition: it assigns definitions to the formulas and predicates (through the structure), as well as values to the variables (through the valuation).

Definition 2.4.10 (*Value*) of a term t under \mathcal{I} is written as $\mathcal{I}(t)$ and defined by $\mathcal{I}(x) = v(x)$ for $x \in \mathcal{V}$ and $\mathcal{I}(f(t_1, \dots, t_n)) = f^{\mathcal{S}}(\mathcal{I}(t_1), \dots, \mathcal{I}(t_n))$

Definition 2.4.11 (*Satisfiability*) \models_{\subseteq} Interpretations \times Form is the smallest relation satisfying

$$\begin{array}{ll} \langle \mathcal{S}, v \rangle \models p(t_1, \dots, t_n) & \text{if } (\mathcal{I}(t_1), \dots, \mathcal{I}(t_n)) \in p^{\mathcal{S}} \text{ where } \mathcal{I} = \langle \mathcal{S}, v \rangle \\ \langle \mathcal{S}, v \rangle \models \forall x. A & \text{if } \langle \mathcal{S}, v[x \mapsto a] \rangle \models A, \text{ for all } a \in U_{\mathcal{S}} \\ \langle \mathcal{S}, v \rangle \models \exists x. A & \text{if } \langle \mathcal{S}, v[x \mapsto a] \rangle \models A, \text{ for some } a \in U_{\mathcal{S}} \end{array}$$

Definition 2.4.12 (*Model*) When $\langle \mathcal{S}, v \rangle \models A$, then $\langle \mathcal{S}, v \rangle$ is a **model** for A . If A does not have free variables, the satisfaction does not depend on the valuation v and we write $\mathcal{S} \models A$

Definition 2.4.13 (*Validity*) When every interpretation is a model, we write $\models A$, and we say that A is **valid**

Definition 2.4.14 (*Satisfiability*) A is **satisfiable**, if there exists at least one model for A .

Example 2.4.15 Given $\forall x.p(x, s(x))$, we a model would be

$$\begin{aligned} U_{\mathcal{S}} &= \mathbb{N} \\ p^{\mathcal{S}} &= \{(m, n) \mid m, n \in U_{\mathcal{S}} \text{ and } m < n\} \\ s^{\mathcal{S}} &= \text{successor function on } U_{\mathcal{S}}, \text{ i.e. } s^{\mathcal{S}}(x) = x + 1 \end{aligned}$$

2.4.2.1 Substitution

Definition 2.4.16 (*Substitution*) Replace all occurrences of a free variable x with some term t in A . To denote a substitution, we write $A[x \mapsto t]$. **Important** All free variables in t must still be free in $A[x \mapsto t]$. If that would not be true anymore, do a α -conversion first.

2.4.3 Quantifiers

2.4.3.1 Universal quantification

Additional rules are needed for the universal quantifier. * side condition is that x is not free in any assumption of Γ

$$\frac{\Gamma \vdash A}{\Gamma \vdash \forall x.A} \forall\text{-I}^* \quad \frac{\Gamma \vdash \forall x.A}{\Gamma \vdash A[x \rightarrow t]} \forall\text{-E}$$

Again here be mindful not to capture free variables.

2.4.3.2 Existential quantification

Additional rules are needed for the existential quantifier. ** side condition is that x is neither free in B nor free in Γ

$$\frac{\Gamma \vdash A[x \mapsto t]}{\Gamma \vdash \exists x.A} \exists\text{-I} \quad \frac{\Gamma \vdash \exists x.A \quad \Gamma, A \vdash B}{\Gamma \vdash A[x \rightarrow t]} \exists\text{-E}^{**}$$

Again here be mindful not to capture free variables.

2.5 Equality

Since equality is such an important concept, it isn't just a predicate, but a separate First-Order Logic (FOL), called **FOL with equality**.

The language is extended by $t_1 = t_2 \in \text{Form}$ if $t_1, t_2 \in \text{Term}$, the semantic entailment \models is also extended by " $\mathcal{I} \models t_1 = t_2$ if $\mathcal{I}(t_1) = \mathcal{I}(t_2)$ ". This definition is the exact intuition of equality of two terms, in that they are equal if their value under the interpretation is equal.

Equality is an equivalence relation, so the following rules apply (ref = reflexivity, sym = symmetry, trans = transitivity):

$$\frac{}{\Gamma \vdash t = t} \text{ref} \quad \frac{\Gamma \vdash t = s}{\Gamma \vdash s = t} \text{sym} \quad \frac{\Gamma \vdash t = s \quad \Gamma \vdash s = r}{\Gamma \vdash t = r} \text{sym}$$

Equality is also a congruence on terms and (definable) relations

$$\frac{\Gamma \vdash t_1 = s_1 \quad \dots \quad \Gamma \vdash t_n = s_n}{\Gamma \vdash f(t_1, \dots, t_n) = f(s_1, \dots, s_n)} \text{cong}_1$$

$$\frac{\Gamma \vdash t_1 = s_1 \quad \dots \quad \Gamma \vdash t_n = s_n \quad \Gamma \vdash p(t_1, \dots, t_n)}{\Gamma \vdash p(s_1, \dots, s_n)} \text{cong}_2$$

2.6 Correctness

For many programs, termination is an important aspect when talking about correctness, as is, of course, that the return value is “correct”.

2.6.1 Termination

Theorem 2.6.1 For a function f defined in terms of other functions g_1, \dots, g_k , for all of which we have $g_i \neq f$ and each g_i terminates, then so does f .

Lemma 2.6.2 Sufficient condition for termination: The arguments are smaller along a **well-founded** order on the function’s domain

Definition 2.6.3 (*Well-Founded Order*) An order $>$ on a set S is **well-founded** if and only if there is no infinite decreasing chain $x_1 > x_2 > \dots$ for $x_i \in S$. An example of such an order is $>$ on \mathbb{N} , denoted $>_{\mathbb{N}}$. Counter example: $>_{\mathbb{Z}}$ (not bounded from below)

Lemma 2.6.4 Let $R \subseteq S \times S$ be a relation on S . Let $s_0, s_i \in S$ and $i \geq 1$. Then $s_0 R^i s_i$ if and only if $s_1, \dots, s_{i-1} \in S$ such that $s_0 R s_1 R \dots R s_{i-1} R s_i$

Definition 2.6.5 $R^+ \equiv \bigcup_{n \geq 1} R^n$, where $R^n \equiv R \circ R^{n-1}$ for $n \geq 2$ and $R^1 \equiv R$

Theorem 2.6.6 If $>$ is a well-founded order on S , then $>^+$ is also well-founded on S

2.6.2 Correctness - Behaviour

We denote that two functions `fac` and `fac2` compute the same function usually as

$$\forall n \in \mathbb{N}. \text{fac } n = \text{fac2 } (n, 1)$$

The two functions are given as follows:

<pre>1 fac :: Int -> Int 2 fac 0 = 1 3 fac n = n * fac (n - 1)</pre>	<pre>1 fac2 :: (Int, Int) -> Int 2 fac2 (0, a) = a 3 fac2 (n, a) = fac2 (n - 1, n * a)</pre>
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An important fact to consider is that testing, while useful to find errors can’t replace a formal proof to show that a function is correct!

These proofs are based on a simple idea: **functions are equations** and thus, we can reason about them through equational reasoning, or more generally, proofs in first-order logic with equality.

Often, especially in Haskell programs, we have cases depending on values. Logically, to prove such a function, we also use case distinction, also referred to as reasoning by cases.

Example 2.6.7 Consider the Haskell function below

```
1 maxi :: Int -> Int -> Int
2 maxi n m
3   | n >= m   = n
4   | otherwise = m
```

To prove that it is correct, we can use reasoning by cases:

We have $n \geq m \vee \neg(n \geq m)$.

We then show that the function is correct for both cases (i.e. LHS and RHS of OR):

C1 $n \geq m$: Then `maxi n m = n` and $n \geq n$

C2 $\neg(n \geq m)$: Then `maxi n m = m`. But $m > n$, so we have `maxi n m` $\geq n$

In this proof we used the **TND** and **\vee -E** (here also called **Case Split**) rules.

So what we have to show, given $Q \vee R$ for any proposition P with case split is that **(1)** P follows from Q and **(2)** P follows from R

2.6.3 Induction

To prove recursive formulas, or more precisely formulated, a formula P (with free variable n) for all $n \in \mathbb{N}$, we can't really do a proof by cases, as there are infinitely many cases (one for each input). Thus: We can use induction to prove recursive formulas or functions.

2.6.3.1 The schema

To prove $\forall n \in \mathbb{N}.P$ (with n free in P), we do the following:

Base case We show that $P[n \mapsto 0]$ is correct

Step case For an arbitrary m not free in P , we show that $P[n \mapsto m + 1]$ is correct under the assumption that $P[n \mapsto m]$

For **well-founded** domains, we have to adjust the induction hypothesis slightly: We assume $\forall l \in \mathbb{N}.l < m \rightarrow P[n \mapsto l]$ and then prove $P[n \mapsto m]$ under our assumption.

2.6.3.2 Induction over Lists

To prove P for all xs in $[T]$, we do the following:

Base case We prove that $P[xs \mapsto []]$ is correct

Step case We prove that $\forall y :: T, ys :: [T].P[xs \mapsto ys] \rightarrow P[xs \mapsto y : ys]$, or in other words: We fix arbitrary $y :: T$ and $ys :: [T]$, which both are not free in P . We then apply our induction hypothesis $P[xs \mapsto ys]$ to prove $P[xs \mapsto y : ys]$

3 Typing

A great type system is essential for all programming languages, but especially so for functional programming languages.

The issue however is that the problem of deciding which expressions are good and which ones aren't is undecidable.

Thus, languages only allow a subset of good expressions. The goal is to make the type system as unrestrictive as possible while still retaining quick, static code analysis.

3.1 Mini-Haskell

This is a stripped down version of Haskell, used here to explore the type system Haskell uses

3.1.1 Syntax

Programs are terms, the core is the lambda-calculus, where \mathcal{V} is the set of variables and \mathbb{Z} the set of integers:

$$t ::= \mathcal{V} \mid (\lambda x.t) \mid (t_1 t_2) \mid \text{True} \mid \text{False} \mid (\text{iszero } t) \mid \mathbb{Z} \mid (t_1 + t_2) \mid t_1 * t_2 \mid \text{if } t_0 \text{ then } t_1 \text{ else } t_2 \mid (t_1, t_2) \mid (\text{fst } t) \mid (\text{snd } t)$$

It is easily possible to add additional syntax and types and we employ syntactic sugar, such as omitting parenthesis.

The types are given by $\tau ::= \mathcal{V}_T \mid \text{Bool} \mid \text{Int} \mid (\tau, \tau) \mid (\tau \rightarrow \tau)$, where \mathcal{V}_T is a set of type variables. The type system is based on typing judgement of form $\Gamma \vdash t :: r$, where Γ is a set of bindings $x_i : \tau_i$ that maps variables to types and can be understood as a typing symbol table.

3.1.2 Lambda calculus

To prove that types are correct, the lambda calculus comes in handy. It is based on the same concept as natural deduction trees

3.1.2.1 Core rules for Lambda-Calculus

$$\frac{}{\Gamma, x : \tau \vdash x :: \tau} \text{Var} \quad \frac{\Gamma, x : \sigma \vdash t :: \tau}{\Gamma \vdash (\lambda x.t) :: \sigma \rightarrow \tau} \text{Abs} \quad \frac{\Gamma \vdash t_1 :: \sigma \rightarrow \tau \quad \Gamma \vdash t_2 :: \sigma}{\Gamma \vdash (t_1 t_2) :: \tau} \text{App}$$

For rule Abs, we require that $x \notin \Gamma$

3.1.3 Further rules for mini-Haskell

3.1.3.1 Base types

$$\frac{}{\Gamma \vdash n :: \text{Int}} \text{Int} \quad \frac{}{\Gamma \vdash \text{True} :: \text{Bool}} \text{True} \quad \frac{}{\Gamma \vdash \text{False} :: \text{Bool}} \text{False}$$

3.1.3.2 Operations

Let $\text{op} \in \{+, *\}$

$$\frac{\Gamma \vdash t :: \text{Int}}{\Gamma \vdash (\text{iszero } t) :: \text{Bool}} \text{iszero} \quad \frac{\Gamma \vdash t_1 :: \text{Int} \quad \Gamma \vdash t_2 :: \text{Int}}{\Gamma \vdash (t_1 \text{ op } t_2) :: \text{Int}} \text{BinOp}$$

$$\frac{\Gamma \vdash t_0 :: \text{Bool} \quad \Gamma \vdash t_1 :: \tau \quad \Gamma \vdash t_2 :: \tau}{\Gamma \vdash (\text{if } t_0 \text{ then } t_1 \text{ else } t_2) :: \tau} \text{if}$$

3.1.3.3 Tuples

$$\frac{\Gamma \vdash t_1 :: \tau_1 \quad \Gamma \vdash t_2 :: \tau_2}{\Gamma \vdash (t_1, t_2) :: (\tau_1, \tau_2)} \text{Tuple} \quad \frac{\Gamma \vdash t :: (\tau_1, \tau_2)}{\Gamma \vdash (\text{fst } t) :: \tau_1} \text{fst} \quad \frac{\Gamma \vdash t :: (\tau_1, \tau_2)}{\Gamma \vdash (\text{snd } t) :: \tau_2} \text{snd}$$

3.1.4 Type inference

Type inference in general fails, if two (or more) branches fail to resolve to unifiable types.

We start a **type judgement** with judgement $\vdash t :: \tau_0$, then build a derivation tree bottom-up. Finally, apply constraints / unification to get possible types.

3.1.4.1 Self application

This means that you apply a function to itself. In Haskell, this is not typeable because there would need to be an infinite function type, but all **Haskell types are finite**

3.1.4.2 Curry-Howard isomorphism

We can also apply the implication introduction and implication elimination rules:

$$\frac{\Gamma, \sigma \vdash \tau}{\Gamma \vdash \sigma \rightarrow \tau} \rightarrow\text{-I} \quad \frac{\Gamma \vdash \sigma \rightarrow \tau \quad \Gamma \vdash \sigma}{\Gamma \vdash \tau} \rightarrow\text{-E}$$

3.2 Natural Number Proofs

To prove $\forall n \in \mathbb{N}. P$, we of course again use induction:

Base Case Show $P[n \mapsto 0]$

Step Case Let $m \in \mathbb{N}$ be arbitrary and not free in P . We then assume that $P[n \mapsto m]$ and show that $P[n \mapsto m + 1]$

Or the same as a natural deduction rule:

$$\frac{\Gamma \vdash P[n \mapsto 0] \quad \Gamma, P[n \mapsto m] \vdash P[n \mapsto m + 1]}{\Gamma \vdash \forall n \in \mathbb{N}. P} \quad m \text{ not free in } \Gamma, P$$

3.2.1 Induction over the natural numbers

In Haskell, we can also define all the natural numbers using

```
data Nat = Zero | Succ Nat deriving (Eq, Ord, Show)
```

Thus the natural numbers are (isomorphic to) the set

$$\text{Nat} = \{\text{Zero}, \text{Succ Zero}, \text{Succ (Succ Zero)}, \dots\}$$

The data type provides two crucial rules for constructing members of `Nat`:

- $\text{Zero} \in \text{Nat}$
- If $x \in \text{Nat}$, then $\text{Succ } x \in \text{Nat}$

The induction stated as a natural deduction rule:

$$\frac{\Gamma \vdash P[n \mapsto \text{Zero}] \quad \Gamma, P[n \mapsto m] \vdash P[n \mapsto \text{Succ } m]}{\Gamma \vdash \forall n \in \text{Nat}. P} \quad m \text{ not free in } \Gamma, P$$

3.2.2 Lists

A possible data type for lists in Haskell is:

```
data L t = Nil | Cons t (L t)
```

A natural deduction rule for induction over lists is:

$$\frac{\Gamma \vdash P[xs \mapsto \text{Nil}] \quad \Gamma, P[xs \mapsto ys] \vdash P[xs \mapsto \text{Cons } y \text{ } ys]}{\Gamma \vdash \forall xs \in \text{L } t. P} \quad y, ys \text{ not free in } \Gamma, P$$

3.2.3 Trees

A possible data type for trees in Haskell is:

```
data Tree t = Leaf | Node t (Tree t) (Tree t)
```

A natural deduction rule for induction over trees is:

$$\frac{\Gamma \vdash P[x \mapsto \text{Leaf}] \quad \Gamma, P[x \mapsto l] \vdash P[xs \mapsto \text{Node } a \text{ } l \text{ } r]}{\Gamma \vdash \forall x \in \text{Tree } t. P} \quad a, l, r \text{ not free in } \Gamma, P$$

3.2.4 Structural Induction

Induction is based on the structure of terms

data $\mathbf{T} \ t = \mathbf{Leaf} \ t \mid \mathbf{Node1} \ (\mathbf{T} \ t) \mid \mathbf{Node2} \ t \ (\mathbf{T} \ t) \ (\mathbf{T} \ t)$

Base Case $T_0 = \{\mathbf{Leaf} \ a \mid a \in t\}$

Step Case $T_i = T_{i-1} \cup \{\mathbf{Node1} \ s \mid s \in T_{i-1}\} \cup \{\mathbf{Node2} \ a \ l \ r \mid a \in t \text{ and } l, r \in T_{i-1}\}$

A natural deduction rule structural induction is:

$$\frac{\Gamma \vdash P[x \mapsto \mathbf{Leaf} \ a] \quad \Gamma, P[x \mapsto s] \vdash P[xs \mapsto \mathbf{Node1} \ s] \quad \Gamma, P[x \mapsto l], P[x \mapsto r] \vdash P[\mapsto \mathbf{Node2} \ a \ l \ r]}{\Gamma \vdash \forall x \in \mathbf{T} \ t. P} \quad (*)$$

(*) a, l, r, s not free in Γ, P

3.3 Interpreters

Interpreters are prevalent in programming languages, database systems, text processors, HDLs, search engines, etc.

They are in concept very simple, as they perform three steps read, evaluate, print.

The implementation of one however is not trivial by any stretch of the imagination.

3.3.1 Read step

During this step, text is turned from text into a more easily handlable format

3.3.1.1 Lexical Analysis

During lexical analysis, the input is turned into tokens. For example: The source code is `position := initial + rate + 60`

The translation is:

- | | |
|--------------------------------------|-----------------------------------|
| 1. Identifier <code>position</code> | 5. Identifier <code>rate</code> |
| 2. Assignment symbol <code>:=</code> | 6. Addition symbol <code>+</code> |
| 3. Identifier <code>initial</code> | 7. Number <code>60</code> |
| 4. Addition symbol <code>+</code> | |

It also removes whitespaces and comments

3.3.1.2 Parsing

The tokens are then turned into an abstract syntax tree.

The syntax is specified by a grammar such as:

$$\begin{aligned} Expr &::= Identifier \mid Number \mid Expr \text{ '+' } Expr \\ Assign &::= Identifier \text{ ':=' } Expr \end{aligned}$$

This can also be represented as a haskell type:

```

1 data Expr = Identifier Ident | Number Num | Plus Expr Expr
2 data Assign = Assignment Ident Expr
3 type Ident = String
4 type Num = Int

```

Since some to be parsed statements are more complex to parse, we may do combinatory parsing.

This is much more powerful as it can handle ambiguous grammars typically found in real programming languages.

We can use for example these parser combinators:

```

1 {-# OPTIONS_GHC -Wno-unrecognised-pragmas #-}
2
3 {-# HLINT ignore "Use lambda-case" #-}
4 {-# HLINT ignore "Use newtype instead of data" #-}
5
6 import Prelude hiding (return, (>>), (>>=))
7
8 data Parser a = Prs (String -> [(a, String)])
9
10 -- Main parser function
11 parse :: Parser a -> String -> [(a, String)]
12 parse (Prs p) = p
13
14 -----
15 -- Basic parsers --
16 -----
17 -- Trivial failure ([] signifies parse failed)
18 failure :: Parser a
19 failure = Prs (const [])
20
21 -- Trivial success without progress
22 return :: a -> Parser a
23 return x = Prs (\inp -> [(x, inp)])
24
25 -- Trivial success with progress
26 item :: Parser Char
27 item =
28   Prs
29     ( \inp -> case inp of
30       "" -> []
31       (x : xs) -> [(x, xs)]
32     )
33
34 -----
35 -- Glue --
36 -----
37 -- Apply both parsers
38 (|||) :: Parser a -> Parser a -> Parser a
39 p ||| q = Prs (\s -> parse p s ++ parse q s)
40
41 -- If first parser fails, apply second parser
42 (+++) :: Parser a -> Parser a -> Parser a
43 p +++ q =
44   Prs
45     ( \s -> case parse p s of
46       [] -> parse q s
47       res -> res
48     )
49
50 -- Sequencing (first parser p, then parser q)
51 (>>=) :: Parser a -> (a -> Parser b) -> Parser b
52 p >>= g = Prs (\s -> [(u, s'') | (t, s') <- parse p s, (u, s'') <- parse (g t) s'])
53
54 -- Simple version of the above

```

```
55 (>>) :: Parser a -> Parser b -> Parser b
56 p >> q = p >>= const q
57
58 -- Parse single character with property p
59 sat :: (Char -> Bool) -> Parser Char
60 sat p = item >>= \x -> if p x then return x else failure
61
62 char :: Char -> Parser Char
63 char x = sat (== x)
64
65 string :: String -> Parser String
66 string "" = return ""
67 string (x : xs) = char x >> string xs >> return (x : xs)
68
69 -- 0 or more repetitions of p
70 many :: Parser a -> Parser [a]
71 many p = many1 p ||| return []
72
73 -- 1 or more repetitions of p
74 many1 :: Parser a -> Parser [a]
75 many1 p = p >>= \t -> many p >>= \ts -> return (t : ts)
```

These are just some of the functions defined. You can find a full mini-haskell and lambda-calculus parser on CodeExpert (at the time of writing this that was the case at least)

3.4 Evaluation

Evaluation is then done using tree traversal as we have already seen in the Haskell section

3.4.1 Lazy Evaluation

Expressions are substituted before evaluation recursively until there are no more expressions to substitute, at which point the expression is evaluated.

This can obviously lead to duplicated evaluation, i.e. a computation reoccurring.

3.4.1.1 In Haskell

In Haskell, this is solved using sharing where the terms are represented in a directed graph.

In pattern matching, the arguments are evaluated only as much as is needed to determine a pattern match.

For guards, the execution proceeds sequentially until success occurs. For instance in an OR statement, only the first statement is evaluated if it evaluates to true

Local definitions are also lazily evaluated (i.e. bound with `where` clauses)

3.4.1.2 Applications

This concept can be used for data-driven programming. For instance, to determine the minimum value of a list, we could use insertion sort and take the head. Due to lazy evaluation, we have way fewer evaluations that need to happen.

Additionally for infinite lists or other infinite data structures, lazy evaluation allows creating a finite representation for the infinite data. It also allows operating on the infinite data given the operation only operates on a finite subset of the data structure.

An application of that is the prime number algorithm Sieve of Eratosthenes:

1. Generate list: `[2 ..]` (list of all natural numbers)
2. Mark the first unmarked number: `head :: [a] -> a` from prelude determines first element
3. Cross out all multiples: `dropMults x ys = filter (\y -> y `mod` x /= 0) ys`
4. Repeat with recursions: `sieve xs = head xs : sieve (dropMults (head xs) (tail xs))`

Another example is Newton's Algorithm to find roots.

3.4.1.3 Correctness

Lazy evaluation makes reasoning about complexity and correctness harder, as types like `[Int]` include

1. finite, everywhere defined lists (e.g. `[1, 3, 5]`)
2. finite lists with undefined elements like `[1, 2, undef]`
3. infinite lists with defined or undefined elements such as `[1..]`

However, induction is only sound for the first kind. More on this later on

4 Language Semantics

4.1 IMP Language

4.1.1 The syntax

The allowed characters:

```
1 Letter = 'A' | . . . | 'Z' | 'a' | . . . | 'z'
2 Digit = '0' | '1' | '2' | '3' | '4' | '5' | '6' | '7' | '8' | '9'
```

And the allowed tokens:

```
1 Ident = Letter { Letter | Digit }*
2 Numeral = Digit | Numeral Digit
3 Var = Ident
```

Arithmetic and Boolean statements could be defined in Haskell as follows

```
1 data Aexp = Bin Op Aexp Aexp | Var String | Num Integer
2 data Op = Add | Sub | Mul
3 data Bexp = Or Bexp Bexp | And Bexp Bexp | Not Bexp | Rel Rop Aexp Aexp
4 data Rop = Eq | Neq | Le | Leq | Ge | Geq
```

Statements could be defined in Haskell as follows

```
data Stm = Skip | Assign String Aexp | Seq Stm Stm | If Bexp Stm Stm | While Bexp Stm
```

We use the following naming conventions for meta-variables:

Variable	Type
n	for numerals (Numeral)
x, y, z	for variables (Var)
e, e', e_1, e_2	for arithmetic expressions (Aexp)
b, b_1, b_2	for boolean expressions (Bexp)
s, s', s_1, s_2	for Statements (Stm)

Meta-variables stand for arbitrary program variables, whereas program variables are concrete variables in a program.

To denote *syntactic equality* of two variables or statements, we use \equiv

4.1.2 The semantics

4.1.2.1 Numerals

The semantic function $\mathcal{N} : \text{Numeral} \rightarrow \text{Val}$ maps a numeral n to an integer value $\mathcal{N}[[n]]$, with $x \in \{0, \dots, 9\}$:

$$\mathcal{N}[[x]] = x \qquad \mathcal{N}[[nx]] = \mathcal{N}[[n]] \cdot 10 + x$$

4.1.2.2 States

A state assigns a value to each program variable. It is a total function and is typically denoted by the meta-variable σ

$$\sigma : \text{Var} \rightarrow \text{Val}$$

To update states, we use the notation $\sigma[y \mapsto v]$, which is given by

$$(\sigma[y \mapsto v])(x) = \begin{cases} v & \text{if } x \equiv y \\ \sigma(x) & \text{if } x \not\equiv y \end{cases}$$

Two states σ_1, σ_2 are equal if they are equal as functions: $\sigma_1 = \sigma_2 \Leftrightarrow \forall x. (\sigma_1(x) = \sigma_2(x))$

4.1.2.3 Arithmetic Expressions

$\mathcal{A} : \text{Aexp} \rightarrow \text{State} \rightarrow \text{Val}$ maps an arithmetic expression e and a state σ to a value $\mathcal{A}[[e]]\sigma$, given by:

$$\begin{aligned}\mathcal{A}[[x]]\sigma &= \sigma(x) \\ \mathcal{A}[[n]]\sigma &= \mathcal{N}[[x]] \\ \mathcal{A}[[e_1 \text{ op } e_2]]\sigma &= \mathcal{A}[[e_1]]\sigma \overline{\text{op}} \mathcal{A}[[e_2]]\sigma\end{aligned}$$

For $\text{op} \in \text{Op}$, $\overline{\text{op}}$ is the corresponding operation $\text{Val} \times \text{Val} \rightarrow \text{Val}$

4.1.2.4 Boolean Expressions

$\mathcal{B} : \text{Bexp} \rightarrow \text{State} \rightarrow \text{Bool}$ maps boolean expression b and a state σ to a truth value $\mathcal{B}[[b]]\sigma$, given by:

$$\mathcal{B}[[e_1 \text{ op } e_2]]\sigma = \begin{cases} \text{tt} & \text{if } \mathcal{A}[[e_1]]\sigma \overline{\text{op}} \mathcal{A}[[e_2]]\sigma \\ \text{ff} & \text{otherwise} \end{cases}$$

Thus, for the `or`, we would have (analogous for `and`)

$$\mathcal{B}[[b_1 \text{ or } b_2]]\sigma = \begin{cases} \text{tt} & \text{if } \mathcal{A}[[b_1]]\sigma = \text{tt} \text{ or } \mathcal{A}[[b_2]]\sigma = \text{tt} \\ \text{ff} & \text{otherwise} \end{cases}$$

`not` is defined as follows:

$$\mathcal{B}[[\text{not } b]]\sigma = \begin{cases} \text{tt} & \text{if } \mathcal{A}[[b]]\sigma = \text{ff} \\ \text{ff} & \text{otherwise} \end{cases}$$

4.1.3 Properties of expression semantics

Since we have recursive definitions for the semantics and syntax, we can use structural induction.

Structural Induction

Recall

For the data structure `Nat`, given by
`data Nat = Zero | Succ Nat`
the structural induction derivation rule is given by

$$\frac{\Gamma \vdash P(\text{Zero}) \quad \Gamma, P(m) \vdash P(\text{Succ } m)}{\Gamma \vdash \forall n \in \text{Nat}. P(n)} \quad m \text{ not free in } \Gamma$$

Where we now write $P(m)$ instead of $P[n \mapsto m]$ and the second premise needs to be proven for all m

4.1.3.1 Inductive Definitions

If we are to introduce a new arithmetic expression $-e$, we could do this in two ways. For one, we could define $\mathcal{A}[[-e]]\sigma = 0 - \mathcal{A}[[e]]\sigma$. This *is* an inductive definition because e is a subterm of $-e$.

If on the other hand we define $\mathcal{A}[[-e]]\sigma = \mathcal{A}[[0 - e]]\sigma$, it is *not* an inductive definition because $0 - e$ is *not* a subterm of $-e$

4.1.3.2 Free Variables

For Arithmetic Expressions

$$\begin{aligned} FV(e_1 \text{ op } e_2) &= FV(e_1) \cup FV(e_2) \\ FV(n) &= \emptyset \\ FV(x) &= \{x\} \end{aligned}$$

For Boolean Expressions

$$\begin{aligned} FV(b_1 \text{ op } b_2) &= FV(b_1) \cup FV(b_2) \\ FV(\text{not } b) &= FV(b) \\ FV(b_1 \text{ or } b_2) &= FV(b_1) \cup FV(b_2) \\ FV(b_1 \text{ and } b_2) &= FV(b_1) \cup FV(b_2) \end{aligned}$$

And finally for Statements:

$$\begin{aligned} FV(\text{skip}) &= \emptyset \\ FV(x := e) &= \{x\} \cup FV(e) \\ FV(s_1; s_2) &= FV(s_1) \cup FV(s_2) \\ FV(\text{if } b \text{ then } s_1 \text{ else } s_2 \text{ end}) &= FV(b) \cup FV(s_1) \cup FV(s_2) \\ FV(\text{while } b \text{ do } s \text{ end}) &= FV(b) \cup FV(s) \end{aligned}$$

4.1.3.3 Substitution

We have already seen this kind of expression in the states, with this explanation it should make a lot more sense intuitively.

A substitution $f[x \mapsto e]$ replaces each free occurrence of variable x in f by e , where f is any expression.

Detailed rules for arithmetic expressions:

$$\begin{aligned} (e_1 \text{ op } e_2)[x \mapsto e] &\equiv (e_1[x \mapsto e] \text{ op } e_2[x \mapsto e]) \\ n[x \mapsto e] &\equiv n \\ y[x \mapsto e] &\equiv \begin{cases} e & \text{if } x \equiv y \\ y & \text{otherwise} \end{cases} \end{aligned}$$

The same for boolean expressions:

$$\begin{aligned} (e_1 \text{ op } e_2)[x \mapsto e] &\equiv (e_1[x \mapsto e] \text{ op } e_2[x \mapsto e]) \\ (\text{not } b)[x \mapsto e] &\equiv \text{not } (b[x \mapsto e]) \\ (b_1 \text{ or } b_2)[x \mapsto e] &\equiv (b_1[x \mapsto e] \text{ or } b_2[x \mapsto e]) \\ (b_1 \text{ and } b_2)[x \mapsto e] &\equiv (b_1[x \mapsto e] \text{ and } b_2[x \mapsto e]) \end{aligned}$$

Substitution Lemma

Lemma 4.1.1

$$\mathcal{B}[b[x \mapsto e]] \Leftrightarrow \mathcal{B}[b](\sigma[x \mapsto \mathcal{A}[e]\sigma])$$

4.2 Operational Semantics

4.2.1 Transition Systems

Definition 4.2.1 (*Transition System*) is a tuple (Γ, T, \rightarrow) , where Γ is a set of **configurations**, T is a set of terminal configurations, with $T \subseteq \Gamma$ and \rightarrow is a transition relation, with $\rightarrow \subseteq \Gamma \times \Gamma$, which describes how executions take place. Big-step transitions are of form $\langle s, \sigma \rangle \rightarrow \sigma'$, e.g. $\langle \text{skip}, \sigma \rangle \rightarrow \sigma$

The transition relations are specified as rules of the form (* optional side-condition, φ_i and ψ transitions)

$$\frac{\varphi_1 \quad \dots \quad \varphi_n}{\psi} \text{ (Name)*}$$

or spelled out, "If $\varphi_1, \dots, \varphi_n$ are transitions (and the *side-condition* is true), then ψ is a transition".

Herein, $\varphi_1, \dots, \varphi_n$ are called **premises** of the rule and ψ is the **conclusion**. A rule without premises is an **axiom rule**.

4.2.2 Big-Step Semantics of IMP

$$\frac{}{\langle \text{skip}, \sigma \rangle \rightarrow \sigma} \text{SKIP}_{NS} \quad \frac{}{\langle x := e, \sigma \rangle \rightarrow \sigma[x \mapsto \mathcal{A}[[e]]\sigma]} \text{ASS}_{NS}$$

Sequential Composition $s; s'$ (s is executed in state σ , then s' in resulting σ' , resulting in σ'')

$$\frac{\langle s, \sigma \rangle \rightarrow \sigma' \quad \langle s', \sigma' \rangle \rightarrow \sigma''}{\langle s; s', \sigma \rangle \rightarrow \sigma''} \text{SEQ}_{NS}$$

Conditional Statements $\text{if } b \text{ then } s \text{ else } s' \text{ end}$ (If b holds, execute s , otherwise execute s')

$$\frac{\langle s, \sigma \rangle \rightarrow \sigma'}{\langle \text{if } b \text{ then } s \text{ else } s' \text{ end}, \sigma \rangle \rightarrow \sigma'} \text{IFT}_{NS} \quad \frac{\langle s, \sigma \rangle \rightarrow \sigma'}{\langle \text{if } b \text{ then } s \text{ else } s' \text{ end}, \sigma \rangle \rightarrow \sigma'} \text{IFF}_{NS}$$

Where the first rule applies if $\mathcal{B}[[b]]\sigma = \text{tt}$

Loop statements $\text{while } b \text{ do } s \text{ end}$ (If b holds, execute s once, whole statement executed in resulting state σ)

$$\frac{\langle s, \sigma \rangle \rightarrow \sigma' \quad \langle \text{while } b \text{ do } s \text{ end}, \sigma' \rangle \rightarrow \sigma''}{\langle \text{while } b \text{ do } s \text{ end}, \sigma \rangle \rightarrow \sigma''} \text{WHT}_{NS} \quad \text{if } \mathcal{B}[[b]]\sigma = \text{tt}$$

If b does not hold, the while statement does *not* modify the state

$$\frac{}{\langle \text{while } b \text{ do } s \text{ end}, \sigma \rangle \rightarrow \sigma} \text{WHF}_{NS} \quad \text{if } \mathcal{B}[[b]]\sigma = \text{ff}$$